2019-2020: Tutorial 10

Exercise 1 (Orientability of the sphere). Prove that \mathbb{S}^n is orientable.

Exercise 2 (Orientability of the projective space). 1. Show that if \widehat{M} is orientable and connected, and $M = \widehat{M}/\Gamma$ is the quotient of M by a group of diffeomorphisms (acting properly discontinuously), one of which reverses the orientation of \widehat{M} , then M is non-orientable.

- 2. Deduce that \mathbb{RP}^{2n} is non-orientable.
- 3. Show that \mathbb{RR}^{2n+1} is orientable.

Exercise 3 (Homotopy equivalence). A smooth map $f: M \to N$ is a homotopy equivalence if there exists a smooth map $g: N \to M$ such that $f \circ g$ is homotopic to id_N and $g \circ f$ is homotopic to id_M . In this case, we say that M and N have the same homotopy type.

- 1. Prove that if M and N have the same homotopy type, then $H^*(M) = H^*(N)$.
- 2. Prove that $H^*(M \times \mathbb{R}^d) = H^*(M)$.
- 3. Prove that $H^*(\mathbb{R}^n \setminus \{0\}) = H^*(\mathbb{S}^{n-1})$.

Exercise 4 (Orientability). 1. Show that any parallelizable manifold is orientable.

- 2. Show that a product of two orientable manifolds is itself orientable.
- 3. Show that the tangent bundle of a manifold is an orientable manifold.
- 4. Give an explicit volume form on the cotangent bundle.

Exercise 5 (Divergence and curl of a vector field (continued)). 1. Let $(E, \langle \cdot , \cdot \rangle)$ be an oriented Euclidean space of dimension 3. Show that any 1-form of E can be written as $\langle X, \cdot \rangle$ for some vector field X on E. Deduce that for every vector field X such that $\operatorname{div}(X) = 0$, there exists a vector field X of E such that $X = \operatorname{curl} A$.

- 2. Show that for every vector field X such that $\operatorname{curl} X = 0$, there exists a smooth function $f: E \to \mathbb{R}$ such that $X = \nabla f$.
- 3. Let $D := \{(0,0)\} \times \mathbb{R} \subset \mathbb{R}^3$. Show that $H^*(\mathbb{R}^3 \setminus D) \simeq H^*(\mathbb{R}^2 \setminus 0)$.
- 4. We recall that $H^1(\mathbb{R}^2 \setminus 0)$ is generated by the angular 1-form $[d\theta]$ and $H^2(\mathbb{R}^2 \setminus 0) = 0$. Let R be the vector field of $\mathbb{R}^3 \setminus D$ defined by

$$R(r\cos\theta,r\sin\theta,z):=-\sin\theta\frac{\partial}{\partial x}+\cos\theta\frac{\partial}{\partial y},\quad\forall r>0,\forall\theta\in\mathbb{R},\forall z\in\mathbb{R}.$$

Show that $H^1(\mathbb{R}^3 \setminus D)$ is generated by $\langle R, \cdot \rangle$.

5. Deduce that for every vector field X of $\mathbb{R}^3 \setminus D$ such that $\operatorname{curl} X = 0$, there exists $\lambda \in \mathbb{R}$ and a smooth $f : \mathbb{R}^3 \setminus D \to \mathbb{R}$ such that $X = \lambda R + \nabla f$. What about those vector fields satisfying $\operatorname{div} X = 0$?

6. Let α be the 1-form $\langle X, \cdot \rangle$. Prove that

$$\lambda = \frac{1}{2\pi} \int_{\gamma} \alpha,$$

where $\gamma(t) = (\cos(t), \sin(t), 0)$.